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Li, Zhongsen; Blanc, Matthieu; Thorel, Luc

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Published in: International Journal of Physical Modelling in Geotechnics

DOI: 10.1680/jphmg.19.00022

Published: 01/05/2020

Document Version Peer-reviewed accepted author manuscript, also known as Final accepted manuscript or Post-print

Please cite the original version:

Li, Z., Blanc, M., & Thorel, L. (2020). Using FBGS to estimate the horizontal response of a monopile in a geotechnical centrifuge. *International Journal of Physical Modelling in Geotechnics*, 20(3), 164-174. Article 1900022. https://doi.org/10.1680/jphmg.19.00022

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# Using Fibre Bragg Grating sensors to estimate the horizontal response of a monopile in geotechnical centrifuge

Zhong-Sen Li, post-doctor<sup>1, 2</sup>; Matthieu Blanc, researcher<sup>1\*</sup>; Luc Thorel, senior researcher<sup>1</sup>

- <sup>1</sup> Laboratory of Geomaterials and Modelling in Geotechnics, Department GERS, IFSTTAR, Route de Bouaye, Bouguenais 44344, France
- <sup>2</sup> Department of Civil Engineering, Aalto University, Otaniemi 02150, Finland

\* Corresponding author: matthieu.blanc@ifsttar.fr, +33 2 40 84 58 18

**Abstract:** A 50-mm-diameter circular aluminium tube was instrumented with two optical fibres that consist of 13 Fibre Bragg Grating sensors (FBGS) for each. The performance of the FBGS was evaluated by applying a series of increasing transversal loads at  $1 \times g$  level and comparing the strains measured by FBGS with those calculated from the Euler-Bernoulli beam theory. Centrifuge test was then conducted at  $100 \times g$  to estimate the transversal response of the calibrated model pile that had been jacked 450 mm into saturated sand and horizontally loaded at 500 mm above the ground. The profiles of the normal strain, bending moment, soil reaction and pile deflection were measured or determined, allowing to construct the soil reaction – pile deflection (P-y) curves. The results confirmed the reliability of the FBGS at  $100 \times g$  by giving satisfactory measurements on bending moments and coherent measurements on shear force at the ground level.

Key words: Centrifuge; Monopile; Transversal loading; Fibre Bragg Grating sensors; Sand

Manuscript revised: 2019-11-01 Number of words: 3746 Number of Table: 2 Number of Figure: 8

### List of notation

- *P* soil reaction (kN/m)
- *y* pile deflection (mm)
- $\varepsilon$  normal strain of the pile
- $\lambda$  peak wavelength of the fibre Bragg grating (nm)
- $\Delta \lambda$  peak wavelength shift (nm)
- *k* gage factor of the optical fibre
- *E* Young modulus (GPa)
- I moment of inertia of an area (m<sup>4</sup> or mm<sup>4</sup>)
- F applied vertical weight during pile calibration (N)
- D external diameter (mm)
- *d* inner diameter (mm)
- *M* bending moment (N.m)
- L Embedded pile length (m)
- *l* lever arm (mm)
- L embedded pile length (m)
- *H* applied horizontal force at the pile head (N)
- *V* shear force (N)
- g gravitational acceleration  $(m/s^2)$
- $d_{10}/d_{50}/d_{60}$  diameter at which 10, 50 or 60% of the sample's mass is comprised of smaller particles (µm)
- $\rho_{d-min}$  minimum dry density (g/cm<sup>3</sup>)
- $\rho_{d-max}$  maximum dry density (g/cm<sup>3</sup>)
- $\Lambda$  distance between two adjacent fringe (nm)
- *n* positive integer
- z depth of the pile embedment (mm)
- $C_u$  coefficient of uniformit

#### 1 1. Introduction

2 Monopile is a typical foundation for offshore wind farms. It takes over 80% of recently installed wind 3 turbines (Wind Europe, 2017) and represent about 15-20% of the total investment. The lifecycle of 4 the monopile is influenced by the horizontal service loads resulting from winds, currents and waves. 5 The generation of horizontal deflection may degrade the foundation soil and as a result trigger the 6 instability problems. Faced with the increasing capacity of the next-generation wind turbines, the 7 dimension of the future monopiles is expected to increase, for example, to as large as 10 m in 8 diameter. For such large-diameter monopiles, current design codes for long and slender piles are 9 deemed inappropriate and new standards need to be developed.

10 In the literature, three experimental methods exist to characterise the response of pile or monopile 11 under transversal loads: i) the full-scale field tests (e.g. Davisson and Salley, 1969; Baguelin et 12 Jézéquel, 1972, Cox et al., 1974; Reese et al., 1974; Ting, 1987; Little and Briaud, 1988; Koukoura 13 et al., 2015; Barbosa et al., 2017; Jardine et al., 2018; McAdam et al., 2018); ii) reduced-scale 14 laboratory tests (e.g. LeBlanc et al., 2010; Abadie et al., 2018) and iii) reduced-scale centrifuge tests 15 (e.g. Georgiadis et al., 1992; Verdure et al., 2003; Rosquoet et al., 2007; Li et al., 2010; Klinkvort 16 and Hededal, 2013, 2014; Klinkvort et al., 2013, 2019; Choo and Kim, 2015; Truong et al., 2018). 17 Each above-mentioned method presents its own inherent advantages and disadvantages. For 18 performing parametric studies in a first step, reduced-scale laboratory and centrifuge tests are more 19 feasible due to the consideration of testing budget. Comparing to laboratory tests, centrifuge tests at 20 elevated gravity have the advantage of reproducing the field stress condition for monopiles. Through 21 carrying out centrifuge tests, researchers were able to test monopiles as large as 50 mm in diameter 22 (e.g. Li et al, 2010, Klinkvort et al., 2019). The pile local strains were measured and then used to determine the soil reaction - pile deflection (P-y) relationship. These results, together with the full-23

scale field tests and reduced-scale laboratory tests, are of interest for the design of next generationmonopiles.

The present study is part of the SOLCYP+ project (France Energies Marines, 2017), which is an extension of the SOLCYP project (Puech and Garnier, 2017). The main objective was to experimentally investigate the response of the model piles under horizontal load in geotechnical centrifuge and then to extrapolate the prototype pile behaviour. Fibre Bragg Grating sensors (FBGS) were used to measure the local strains and to determine the moment profile of the pile. Experimental results are presented following the local pile analysis (Garnier, 2013).

#### 32 2. Principle and geotechnical application of FBGS

Exposing the Germanium-doped optical fibre to the spatial pattern of ultraviolet light (e.g. Hill and Meltz, 1997; Kreuzer, 2006) can artificially alter the refractive index of the fibre and form a periodic modulation of the refractive index (i.e., grating). When a beam of light passes a grating, part of the light will be reflected and the other be transmitted. The reflected lights accumulate and form a peak if an integer of the light wavelength fits into two times of the fringe spacing, as shown in Figure 1.

38 Under the effect of the external stress or temperature, the optical fibre shrinks or swells. This 39 shrinkage-swelling results in a change in grating period and as a result a corresponding shift of the 40 reflected peak wavelength in the recorded spectra. Under temperature-controlled condition, the strain 41 ( $\varepsilon$ ) can be calculated with the peak wavelength shift ( $\Delta\lambda$ ) by the following formula:

42 
$$\varepsilon = \frac{\Delta \lambda}{\lambda k} \tag{1}$$

43 where  $\lambda$  (nm) is the initial peak wavelength under null external stress (i.e., reference scan),  $\Delta\lambda$  (nm) 44 is the peak wavelength shift and k, the gage factor, is equal to 0.78 for the fibre used in this study. 45 As the FBGS has very small dimension (e.g., diameter of several hundred micro-meters), it can be 46 adhered on or embedded into the piles or beams without significantly changing their geometry and 47 mechanical property. For such reason, it has been increasingly used. In geotechnical laboratory and 48 field testing, FBGS have been used to measure the load transfer of the model pile (e.g., Lee et al., 49 2004), the strain distribution along the soil nails during pull-out test (e.g., Zhu et al., 2007, 2011; 50 Hong et al., 2017) and the transversal displacement of ballast under cyclic loading conditions (e.g., 51 Hussaini et al., 2015). Besides, FBGS have been used to monitor the dynamic process of the wind 52 turbine blades (e.g., Park et al., 2011), large pile under vertical driving conditions (e.g., Doherty et 53 al., 2015) and strains of buried pipelines under different external loads (e.g. Glisic and Yao, 2012; 54 Simpson et al., 2015; Ni et al., 2018).

55 However, the report of the FBGS in geotechnical centrifuge is limited. Kapogianni et al. (2010) 56 investigated the performance of FBGS in a drum centrifuge at ETH Zurich. The FBGS gave coherent 57 measurements at different g-level (0-100 g) even though the unstable measuring signal was observed 58 due to the movements of the FBGS cables. Da Silva et al. (2016) reported their experience on FBGS 59 instrumentation and calibration in centrifuge test at the University of Cambridge. A first issue that 60 they considered was the location and orientation of the fibre optic interrogator. In their study, the interrogator was placed on the centrifuge beam as close as possible to the centre to minimise the 61 62 gravitational acceleration experienced by the interrogator. In addition, the interrogator box was 63 orientated such that the axis of the fans aligned with the direction of the gravitational acceleration to 64 minimise impact of g-level on the operation of the interrogator. After these efforts, the authors found that the interrogator remained securely in place with g-level up to 40 g (i.e., 6 g for the interrogator). 65 66 Excellent correlation was achieved between the strains measured by FBGS and those by LVDT, with 67 the difference generally smaller than 5%. To avoid the high g-forces within the interrogator, Correia et al. (2016) reported a new method to place the FBGS interrogator. This method consists of using a 68

69 fibre optic rotary joint and placing the interrogator outside of the centrifuge. At Chang'an University 70 (China), Weng et al. (2016) conducted a series of centrifuge tests, using both FBGS and strain gauge 71 to measure the vertical strains of a jacked steel pile previously soaked by water. The difference 72 between the strains measured by FBGS and the strains measured by strain gauges was, in most cases, 73 within 10%.

In conclusion, the FBGS i) provides a precise, reliable and convenient method to monitor strain change of piles and pipes; ii) allows multiple strain measurements with a single fibre; iii) is easy to be installed and suitable under both static and dynamic load conditions and iv) is rarely used in geotechnical centrifuge. Compared to the strain measuring methods that the authors previously adopted (e.g., gluing the strain gages outside or even inside the tube in Rosquoët et al., 2007 and El Haffar et al., 2019), the choice of the optical fibres in this study was mainly to maintain the wall thickness of the tube while working on an open-ended model pile.

#### 81 **3. Instrumentation and calibration of the model pile**

82 The geometric and mechanical characteristics of the model pile are described in Figure 2 and Table 83 1. The choice of an aluminium tube instead of a steel bar allows to respect the key scale factor of the 84 rigidity (EI) while maintaining a suitable tube thickness for embedding FBG sensors. Besides, 85 aluminium has been commonly used in geotechnical centrifuge to reproduce the behaviour of steel structures (e.g. Ng et al., 2015; Saiyar et al., 2016). The pile was chiselled with two semi-cylindrical 86 87 grooves that are diametrically opposed. The radius of the grooves is 0.5 mm, i.e., 1/5 the wall 88 thickness of the pile. Two 200-micrometer-diameter optical fibres were laid straight in the grooves 89 and then sealed by a bi component cold curing epoxy, i.e., X120 adhesive. X120 adhesive was chosen 90 mainly due to its easy usage and good strain transfer property (HBM, 2019b). Another consideration 91 was that the stiffness of the adhesiveness is smaller than that of the pile so that the local gauge

92 hardening effect can be avoided. Placing two optical fibres in an extension-compression 93 configuration, i.e., diametrically opposed as shown in Figure 2a, aimed to compensate the temperature effect on the measurement. This effect can be compensated by averaging the difference of the two 94 95 measured strains (i.e.,  $\varepsilon_{av} = (\varepsilon_{ext} - \varepsilon_{comp})/2$ ) as a temperature change has identical effect on both fibres 96 in terms of the peak wavelength shift, e.g., one fibre being compressed and features a negative strain, 97 whereas the other being stretched and has a positive strain. Within each optical fibre, 13 FBGS were 98 integrated and distributed every 25 mm for the first eight FBGS (#1 - #8) and every 50 mm for the 99 rest (#9 - #13). Such a configuration allows to measure the pile strains at 13 different positions ranging from 0 - 425 mm away from the FBGS #1, as shown in Figures 2 and 3. 100

101 The calibration of the model pile is intended to compare the the strain measured by FBGS and that 102 calculated from the Euler-Bernoulli beam theory. Two calibrating methods are proposed: i) the pile 103 clamped at one end (i.e., cantilever beam) and ii) the pile put on two rigid supports (e.g., simply 104 supported beam). The apparatus and the corresponding schematic drawing are presented in Figure 3. 105 To avoid the possible damage on the pile end in particular for the cantilever beam configuration where 106 the pile was clamped only 10 mm at the end, the maximum applied weight F was limited, for example 107 100 N and 500 N for the cantilever and simply supported beam, respectively. For this reason, the 108 calibration strains were within 350 microstrain (10-6), which cannot cover the full range of the 109 following centrifuge tests. Transversal loads were applied at  $1 \times g$  level with an incremental ratio of 110 about 2, i.e., 20, 50, 100 N for the cantilever beam and 20, 50, 100, 200 and 500 N for the simply 111 supported beam. In order to evaluate the performance of the FBGS under both tensile and compressive conditions, the pile was calibrated at  $0^{\circ}$  (initial position) and  $180^{\circ}$  (turning the pile over). 112 113 As the transversal load increases, the model pile deflects and generates tensile or compressive strains. 114 These strains can be on the one hand calculated based on the direct measurements of the FBGS as shown in Equation 1, and on the other hand determined by the Euler-Bernoulli beam theory using thefollowing formula:

$$\varepsilon = \frac{MD}{2EI}$$
(2)

where M is the moment at different sections, F, the applied transversal force, D, the outside diameter of the pile, E, the Young modulus of the pile and I, the moment of inertia of the section.

120 For the cantilever beam configuration, the moment *M* is:

121 
$$M = F \cdot (500 + z_{FBGS})$$
(3)

122 and for the simply supported beam, the moment *M* is:

123 
$$M = \frac{F \cdot 215 \cdot (440 - z_{FBGS})}{955} \tag{4}$$

124 where  $z_{FBGS}$  is the position of the FGBS in mm, as illustrated in Figure 3.

125 Figure 4 presents the calibration results of the model pile. When the pile is clamped on one tip (i.e., cantilever beam), the transversal loads applied on the other tip generate bending moment, shear force 126 127 and normal stress at the cross-section of the pile. On the upper side of the neutral axis, the normal 128 stresses and strains are tensile, and on the lower side, they are compressive. The strains measured by 129 the two optical fibres (A and B) are presented in the first and second diagrams of Figure 4a, which 130 correspond to the pile at the initial position and turned 180° over, respectively. For the applied loads, 131 most experimental results (i.e., points) situate on or are very close to the correlation lines according 132 to the Euler-Bernoulli beam theory, i.e., Equation 2. Exceptions are the measurements by the FBGS 133 #13, as shown in Figure 4a. The strains measured by FBGS #13 deviate the theoretical values and the 134 difference becomes more pronounced at larger load levels (e.g., 100 N). The main reason for such inaccurate measurements is that the FBGS #13 is too close (i.e., 15 mm) to the clamp, where shear 135

136 strains are more significant. In such case, both the Saint Venant principle and the Euler-Bernoulli 137 beam assumptions are not satisfied. The relative difference of the strain measured by FBGS ( $\varepsilon_{FBGS}$ ) 138 and that determined by Euler-Bernoulli beam theory ( $\varepsilon_{E-B}$ ) ranges from -4.74 to 3.46% for optical fibre A at initial and 180° turn-over positions if the FBGS #13 is not taken into account. Taking the 139 140 average value of the four measured strains (i.e., fibre A at 0° and 180°, and fibre B at 0° and 180°), the bending moments are calculated with Equation 2 and then compared with the theoretical 141 142 correlation lines, as shown in the third diagram in Figure 4a. Apart from the last point by FBGS #13, 143 the experimental points are in very good agreement with the theoretical prediction.

144 When the pile is supported by two tips (i.e., simply supported beam) and the transversal loads are 145 applied in between, strains are in tension on the lower side and in compression on the upper side. 146 Similarly, the experimental points, excluding those measured by FBGS #13, are located around the 147 correlation lines (Figure 4b). However, for the maximum transversal load, the measured strains are 148 deviated from those calculated according to Euler-Bernoulli beam theory. The FBGS measurements 149 derivate from -11.99 to 4.89% from the theoretical predictions for FBGS #1-8. The relative difference 150 increases significantly for FBGS #9-13. This may result from many aspects in such a free system 151 where both the stress concentration and pile movement are possible. As concerning the moment 152 profiles, results in the third diagram of Figure 4b shows better accordance between the experiment 153 and theoretic correlations, with their difference generally smaller than 5%.

#### 154 **4.** Pile behaviour under transversal loads in centrifuge test

#### 155 4.1 Preparation of the centrifuge test

The experimental study was carried out at the IFSTTAR large beam centrifuge (D = 11 m) inaugurated in 1985 (Corté and Garnier, 1986).The centrifuge can generate a maximum gravitational acceleration of 100 g in the bracket for a sample mass up to 2 tons. The FS22DI Industrial BraggMETERInterrogator box from HBM was placed in the data acquisition chamber that is attached to the rotation centre. The longitude direction of the interrogator was in line with the centrifuge arm. The gravitational acceleration experienced by the interrogator is estimated about 1/15 of the centrifuge basket. The wavelengths of the 13 FBGS at reference scan range from 1520-1580 nm and increase every 5 mm. To prepare for the centrifuge test, three steps were employed: i) model sand preparation, ii) pile installation and iii) load application.

165 The model soil was the Fontainebleau NE34 poorly graded sand (Table 2). Using the automated 166 raining technique (Garnier 2001), the sand was dropped from a constant height (70 cm in this study) 167 and then pluviated into a 1200 mm (length) by 800 mm (width) by 720 mm (height) rectangular 168 strongbox. The depth of the sand mass was 560 mm and the relative density was 81%. To simulate 169 the prototype condition where the foundation is under water, the sand was saturated by slowly (about 170 6 hours) injecting water through four draining channels located at the bottom of the strongbox. The 171 attained water table was about 30 mm above the sand surface. The effective volumetric weight of the 172 saturated sand was  $10.3 \text{ kN/m}^3$ .

173 Concerning the pile installation, the instrumented model pile (Figure 2) was pushed into the sand at 174 1×g level by a hydraulic jack. The jacking speed was 1 mm/s and the attained depth is 450 mm, i.e., 175 9D. The sand level inside the pile was checked and there was no plug generated. After pile installation, 176 an electric actuator was mounted on two supporting beams that perpendicularly placed on the 177 longitudinal edges of the strongbox. The actuator has a stroke of 150 mm and can measure the load with a precision of 0.1 N for a range from 0 - 5 kN. At the end of the piston, a force transducer and 178 179 a loading fork were integrated, aiming to measure and control the applied horizontal load. In front of 180 the actuator, a laser displacement transducer, with measuring range of 120 mm and resolution of 20 181 µm, was fixed on a supporting beam. This allows to monitor the pile deflection at 410 mm above the 182 ground level. The established experimental set-up is schematically shown in Figure 5.

Centrifuge test was performed at 100×g level. Horizontal load was applied through the centre of the cross section by pushing the steel rod that crosses the monopile perpendicularly to the instrumentation plan (Figures 2 and 3). The loading point situates at 500 mm (i.e. 10D) above the ground level. The loading was displacement-controlled with a rate of 1 mm/s at the actuator level and terminates at 50 mm (i.e. 1D). The measurements of the FBGS, the laser and force transducer were recorded and registered every 0.02 second (i.e., 50 Hz).

#### 189 4.2 Horizontal response of the model pile

190 In Figure 6a, the normal strains measured at each incremental force (every 0.25 kN until 1.75 kN) 191 were plotted versus the pile depth As the applied horizontal load *H* increases, the normal strains within 192 the pile increase as well. Under the same H, normal strains first slightly increase with depth, reach to 193 the maximum at the depth of 100 mm and then decrease almost to zero at 425 mm below the ground 194 level. The average value of the tensile and compressive strains was used to determine the bending 195 moments and the used equation was shown in Figure 6b. At the ground level, the moments measured 196 by FBGS (empty circular points) are very close to the moments calculated from H (solid square 197 points), confirming the reliability of the FBGS under flight condition. At the pile end (FBGS #13, z 198 = 425), the bending moments are close to zero. The discrete moments along the depth need to be 199 fitted into continuous so that further calculation can be proceeded. In Haiderali and Madabhushi 200 (2016), the authors compared different curve fitting techniques and found that the cubic and cubic B-201 splines gave more consistent and accurate P-y curves. In this study, the cubic splines function was 202 used to interpolate the experimental results. According to the beam theory, the shear force V and the 203 transversal distributed loads along the pile P (equal to the soil reaction) can be obtained by solving 204 the first and second derivatives of the moment profiles (i.e. cubic splines), respectively. Due to the 205 lack of the experimental results above the ground surface and below the pile tip, the algorithm of the 206 cubic spline forces the spline approximate the end points (i.e., FBGS #1 and FBGS #13) in a default 207 way, considering the second derivative of the spline to be zero. Such algorithm is normally reasonable 208 for FBGS #1 as the second derivative of the bending moment (i.e., soil reaction) should be 209 theoretically null at the ground level, however, probably incorrect for FBGS #13 because the soil 210 reaction at the pile tip should not be zero. As a result, the first and second derivatives of FBGS #13 211 (i.e. pile depth from 375-425) are not necessarily significant and were not determined. In Figures 6c 212 and 6d, the V and P profiles are presented. For the former, V at the ground level are coherent with H213 applied by the actuator. Slight difference is due to uncertainties in finding the first derivative 214 accurately as it lacks experimental points above the ground surface. Concerning the P profile, as H 215 increases, the pile rotation centre defined here as the point where the soil reaction is nil, P = 0216 increases from 210 - 275 mm (i.e., 4.2 - 5.5 D) below the ground level.

Finding the second-order definite integral of the moment profiles, one may obtain the pile transversal 217 218 deflection y. This was usually achieved by solving a simultaneous equation that contains two 219 integration constants. Two limit conditions are introduced in this study. The first one is the pile 220 deflection measured by the electric actuator at the pile head. The second is the null pile deflection (y 221 = 0) at the rotation centre, which was determined by finding the depths of the null reaction (P = 0), 222 as presented in El Haffar et al. (2019). Figure 7 presents the pile horizontal deflection at different H223 values. Due to the large embedment depth (i.e., 450 mm or 9D), pile deflections are close to zero 224 below the rotation centre (e.g., 300 - 450 mm below the ground surface). Presented also are the pile 225 deflections measured by the laser transducer. As *H* increases, the laser provides extra measurements 226 that are comparable with the measurements provided by the electric actuator.

227 *P-y* curves are obtained by plotting the pile deflection *y* versus the soil reaction *P* at different depths 228 (e.g., the depth of the FBGS). In Figure 8, each curve demonstrates the *P-y* relationship as *H* increases 229 from 0.25 - 1.75 kN. *P* is positive above the pile rotation centre and negative under. The initial soil 230 stiffness, i.e., the initial slope of the *P-y* curve, increases as the embedment depth increases (from the ground surface to the pile tip). For the soil at a certain depth (e.g., z = 75 mm), its stiffness decreases as the horizontal load *H* increases. In this study, a plateau is reached only for the second level, z = 25mm. For deeper levels (e.g. z = 50 - 225 mm), the *P*-*y* curves show a tendency to be stabilized. However, much more lateral displacement is needed to reach such limit.

#### **5.** Conclusions

A model pile was instrumented with two diametrically-opposed optical fibres. The instrumented pile was calibrated at 1×g and then subjected to lateral loading in centrifuge at 100×g. The experimental results show that:

- All the 26 FBGS survived in the  $100 \times g$  centrifuge test;
- At the ground level, the moments determined by FBGS are in accordance with the moments 241 calculated from the transversal force;
- Shear forces at the ground level are slightly larger than the applied transversal forces. Such
   difference mainly results from the difficulty of the accurate derivation operation at the ground
   level.
- The pile local behaviour is characterized: under the effect of the increasing horizontal load, pile rotates at the depth 210 - 275 mm (i.e., 4.2 - 5.5*D*) below the ground level. Due to the large embedment depth, the pile deflection below the rotation centre close to zero. The P-y curves at different depths were also determined.

Material	Prototype	Model
L (m)	50	0.5
D (m)	5	0.05
d (m)	4.5	0.045
E (GPa)	74 GPa	74 GPa
EI (N.m <sup>2</sup> )	7.8×10 <sup>11</sup>	7.8×10 <sup>3</sup>

Table 1. Geometric and mechanical characteristics of the pile

Sand	Cu	d <sub>50</sub>	$ ho_{d-min}$	$\rho_{d\text{-max}}$
	$(=d_{60}/d_{10})$	(µm)	$(g/cm^3)$	$(g/cm^3)$
NE34	1.53	210	1.434	1.746

Table 2. Characteristics of the Fontainebleau NE34 sand

249

#### Acknowledgement

This work benefited from France Energies Marines and State finance managed by the National Research Agency under the Investments for the Future program bearing the reference SOLCYP+ ANR-10-IEED-0006-18. Assistances from the technical staffs of the centrifuge group and discussion with Dr. Thierry Dubreucq are acknowledged.

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# **FIGURE CAPTIONS**

Figure 1 Working principle of the Fibre Bragg Grating sensors

Figure 2 Instrumentation of the model pile

- Figure 3 Experimental set-up for the calibration of the instrumented pile
- Figure 4 Measurements of the FBG sensors for the calibration test
- Figure 5 Schematic drawing of the transversal loading system in the centrifuge
- Figure 6 Profile of (a) the measured strains, (b) the bending moment, (c) the shear force and (d) the soil reaction (i.e., the distributed load)
- Figure 7 Deflection of the pile below and above the ground level
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(b) Wave propagation in the Bragg optical fibre

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(a) Cantilever beam configuration

(b) Simply supported beam configuration

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Figure 8 Soil reaction (P) versus the normalized pile deflection (y/D)