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Single core and multicore aggregates from a polymer mixture: A dissipative particle dynamics study

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Hypothesis: Multicore block copolymer aggregates correspond to self-assembly such that the polymer system spontaneously phase separates to multiple, droplet-like cores differing in the composition from the polymer surroundings. Such multiple core aggregates are highly useful capsules for different applications, e.g., drug transport, catalysis, controlled solvation, and chemical reactions platforms. We postulate that polymer system composition provides a direct means for designing polymer systems that self-assemble to such morphologies and controlling the assembly response.

Simulations: Using dissipative particle dynamics (DPD) simulations, we examine the self-assembly of a mixture of highly and weakly solvophobic homopolymers and an amphiphilic block copolymer in the presence of solvent. We map the multicore vs single core (core–shell particles) assembly response and aggregate structure in terms of block copolymer concentration, polymer component ratios, and chain length of the weakly solvophobic homopolymer.

Findings: For fixed components and polymer chemistries, the amount of block copolymer is the key to controlling single core vs multicore aggregation. We find a polymer system dependent critical copolymer concentration for the multicore aggregation and that a minimum level of incompatibility between the...
1. Introduction

Block copolymers self-assemble to various morphologies spontaneously [1–6]. The assembly is driven by demixing (or micro-phase separation) of the chemically dissimilar polymer segments into different domains [6–8]. In recent years, complex and fascinating supramolecular structures of block copolymers [9,10] such as micelles [11,12], films [13,14], tubules [15], and vesicles [16,17] have been produced by self-assembly. The assembly is driven by a combination of entropy and enthalpy [18–21]. Concentration, degree of polymerization, and miscibility of the components are the key parameters determining the final assembled morphology [21].

A particularly interesting type of self-assembling phase is the formation of multicore micelles. In macroscopic assembly, this corresponds to the droplet phase [22,23]. In both multicore micelles and the droplet phase, isolated domains of one polymer composition are surrounded by a corona phase with a differing composition. This leads to assemblies with several cores, see e.g. Refs. [24–29]. Multicore assemblies have attracted attention not only for academic reasons but also for their potential use in water purification, catalysis, pharmacology, electronics, and oil recovery [20,30–37].

Both experimental and theoretical research works have reported multicore micelles as one of their obtained results. Multicore micelles were formed by Duxin et al. [28] in cadmium sulfide (CdS) quantum dots (QDs) formation within poly(ethylene oxide)-block-poly(styrene-block-poly(acrylic acid)) (PEO-b-PS-b-PAA) triblock copolymer. Iatridi et al. [27] explored a novel multisegmented, multiarm star-shaped terpolymer bearing PS hydrophobic arms and P2VP-b-PAA diblock copolymer amphoteric arms in aqueous media leading to multicore large compound micelles. In another research work, Ueda et al. [26] observed a single core to multicore transition in amphiphilic alternating copolymer samples of sodium maleate and dodecyl vinyl ether in a solution-state self-assembly system composed of linear ABC terpolymers consisting of a solvophilic mid-block and two mutually incompatible solvophobic end blocks. Using self-consistent field theory based calculations, Guo et al. [50] could observe wormlike multicore micelles for π-shaped ABC block copolymers with a hydrophilic backbone block A and hydrophobic graft blocks B and C. The findings showed how the distance of the two graft blocks of the π-shaped block copolymers controls the morphology of wormlike micelle micelle. Chen et al. [29] identified multicore colloidal particles formed by self-assembling a three-arm star-shaped polymer using dissipative particle dynamics (DPD) simulations.

Although these studies demonstrate several interesting examples of realizations for stable, self-assembling block copolymer multicompartment and multicore aggregates, the synthesis methods are hard to implement. To fully utilize and benefit from the technological potential of the heterogeneous, compartmentalized molecular environment of the multicore and multicompartment aggregates, more economical and straightforward approaches to form multicore and multicompartment assemblies are needed. In our previous work [49], we reported multicore aggregation in a simple, three-component polymeric system based on DPD simulations. The focus polymer system composed of a mixture of highly and weakly solvophobic homopolymers and an amphiphilic block copolymer in a solvent medium. We extracted guidelines for the necessary solvophobicity differences in the polymer mixture components for spontaneous multicore assembly. Here, we provide a systematic characterization of the interdependencies of a simple three component linear copolymer system to self-assemble into multicore assemblies of several co-existing length scales vs traditional polymer core–shell micelles. The findings center on generalizations of assembly dependence, in particular necessity for a critical amount of copolymer, interconnected with the miscibility difference of the component species, as means to induce and control the dual length scale assembly. The findings suggest possible transition mechanisms and morphological transition variables to aid design of polymer self-assembly systems.

2. Methods

Dissipative particle dynamics (DPD) simulations [51–53] were used to examine the polymer system. DPD is a coarse-grained bead-based simulation method that can be used to describe at mesoscale complex liquids. The use of soft potentials and capturing hydrodynamics make the approach useful for examining the assembly and dynamics of soft matter in the liquid phase. While the approach captures assembly and morphology changes very efficiently, retaining chemical mean characteristics of the modelled molecular region, the coarse-graining loses strongly localized and microscopic level effects, such as charge-charge pairing effects or hydrogen bonding.

The total force $\mathbf{F}_i$ acting on particle $i$ is composed of pairwise conservative force $\mathbf{F}^C_{ij}$, friction force $\mathbf{F}^D_{ij}$, stochastic force $\mathbf{F}^R_{ij}$, and
a harmonic spring force $F_{ij}^c$ between the polymer beads such that

$$F_{ij}^c = \sum_{i,j} \left( F_{ij}^C + F_{ij}^0 + F_{ij}^R + F_{ij}^S \right)$$

(1)

In this, $F_{ij}^C = a_{ij}^c \omega^c(r_{ij}) \vec{e}_{ij}$, the hydrodynamic drag is captured by $F_{ij}^R = -\gamma \omega^H(r_{ij}) \left( \vec{v}_{ij} \cdot \vec{e}_{ij} \right) \vec{e}_{ij}$ and $F_{ij}^S = \sigma \omega^H(r_{ij}) \theta_{ij} \vec{r}_{ij}$ corresponds to thermal fluctuations and has Gaussian distribution. A harmonic spring force $F_{ij}^c$ with spring force constant $k = 4$ in DPD reduced units, is set between neighboring polymer beads to keep the polymer beads connected [19,53,54]. The total force $F_{ij}$ (Eq. (1)) is summed over all particles $i \neq j$ for the conservative, friction, and stochastic forces at separations less than the cutoff radius $R_c$. The spring force acts only between consecutive beads in a polymer chain.

Additionally, $r_{ij} = r_i - r_j$, $r_y = |r_{ij}|$, and $\vec{e}_{ij} = \frac{r_{ij}}{r_{ij}}$, with $r_i$ and $r_j$ being the position vectors of particle $i$ and $j$, respectively. The relative velocity $\vec{v}_{ij} = \vec{v}_i - \vec{v}_j$, where $\vec{v}_i$ and $\vec{v}_j$ capture the velocities of particle $i$ and $j$, respectively. The interaction parameter $a_{ij}^c$ captures repulsion between the particles, $\gamma = 4.5$ is the friction coefficient, and $\sigma = 3$ the noise amplitude governing the intensity of the stochastic force. The conservative, dissipative, and random forces each include their own weight function called $\omega^c$, $\omega^P$, and $\omega^H$, respectively. For the conservative force, $\omega^c(r_{ij}) = 1 - \frac{r_{ij}}{R_c}$ for $r_{ij} < R_c$ and $\omega^c(r_{ij}) = 0$ for $r_{ij} \geq R_c$. The two weight functions $\omega^P(r_{ij})$ and the $\omega^H(r_{ij})$ can be chosen arbitrarily but their relation is $\omega^P = \left( \omega^c(r_{ij}) \right)^2$ [52]. A simple form of $\omega^P$ and $\omega^H$ was chosen following Groot and Warren [53] with $\omega^P(r_{ij}) = \left( \omega^c(r_{ij}) \right)^2 = \left( 1 - \frac{r_{ij}}{R_c} \right)^2$ for $r_{ij} < R_c$ and $\omega^P(r_{ij}) = \left( \omega^c(r_{ij}) \right)^2 = 0$ for $r_{ij} \geq R_c$. The amplitudes follow $\sigma^2 = 2g/k_BT$ based on fluctuation–dissipation theorem, so that the dissipative force and random force together act as a thermostat. $\theta_{ij}(t)$ is a Gaussian random variable with zero-mean and unit variance [54]. DPD simulations keep the particle number, volume, and temperature constant and take place in the NVT ensemble.

A modified velocity-Verlet algorithm is used to integrate the equations of motion with a time step $\Delta t = 0.05$ and weighting factor $\lambda = 0.65$. Unit normalization follows standard DPD reduced units such that the cutoff radius $R_c$, the bead mass $m$, and $k_BT$, where $k_B$ is the Boltzmann constant and $T$ the temperature, are used as the distance, mass, and energy units. This leads to $R_c = m = k_BT = 1$ and the time unit $\tau = (mr^2 / k_BT)^{1/2} = 1$. The particle number density in the system is set to $\rho = 3$. With this choice, the relationship between the DPD $a_0$ interaction parameter and Flory-Huggins mixing parameter $\chi_{ij}$ is

$$a_0 - a_i = 3.27 \chi_{ij}$$

(2)

A value of $a_0 = 25$ is set for the same type of DPD particles. A summary of the DPD reduced units and their conversions, as well as those of the model parameters are presented in the Supporting Material in Table S1.

### 2.1. Model construction details

The examined system consists of an amphiphilic diblock copolymer and two linear homopolymers, one weakly and the other strongly solvophobic, mixed in a solvent. All examined chains correspond to oligomeric chain length range. To simplify the modelling system, the blocks of the copolymer are considered identical in their interactions to the two homopolymer species. This leads to three different types of DPD beads in the system A, S, and W. The two former compose the two homopolymers $A_n$ and $S_n$ and the diblock copolymers $A_iS_l$, where the subindexes refer to the number of beads in the chain, see Fig. 1. The solvent is described by beads W. All beads have the same size and mass $m = 1$. Table 1 summarizes the examined concentrations, chain lengths and chain length variable indices used in the work. The concentrations were chosen to be likely to result in finite size aggregates, and to be typical aqueous solution concentrations of such polymer solutions. The concentration of species $i$, $C_i$, is calculated as the species fraction, i.e. the number of beads of species $i$ divided by the total number of DPD beads in the system. As the DPD beads all have equal volume and mass, this fraction leads to weight and volume concentration percentages. The copolymer concentration $C_{A_iS_l}$ and the weakly hydrophobic homopolymer chain length are the two main parameters studied in this research as morphology controlling factors.

The interaction parameters are identical to those in our previous work [49]:

$$a_0 = \begin{bmatrix} A & S & W \\ A & 25 & 72 & 115 \\ S & 72 & 25 & 30 \\ W & 115 & 30 & 25 \end{bmatrix}$$

(3)

For polymer solutions, the transition to a poor solvent happens at $\tau T = 0.5$. Mixing parameter values above that critical value correspond to poor solvent. For theta condition, this leads to DPD interaction between polymer and solvent $a_{0W} = 26.63$, following Eq. (2). As in our model, the S-W interaction parameter $a_{0W} = 30$ exceeds this, some phase separation can be expected. On the other hand, A and S are chosen to be strongly immiscible with $a_{AS} = 115$. This leads to a system that it is composed of solvophobic homopolymers A, amphiphilic copolymers composed of A and S blocks, and a slightly solvophobic homopolymer S.

The simulations were carried out using the LAMMPS (Large-scale Atomic/Molecular Massively Parallel Simulator) package [55,56] in a cubic simulation box $40R_c \times 40R_c \times 40R_c$ in size and periodic in all three dimensions. The simulation times were between $5 \times 10^5$ and $5 \times 10^6$ steps. Configurations and corresponding data were saved as frames at 2000 DPD steps intervals. Unless otherwise said, all presented data results from averaging over the last 20 saved frames. The analyzed data period corresponds to equilibrated systems; equilibration was evaluated against time evolution of aggregate structure (data provided in Supplementary Material Figure S1). Standard deviation is used as error estimate. Presented snapshots correspond to the final simulation configurations.
3. Results and discussion

3.1. Block copolymer concentration

First, the effect of block copolymer concentration, \( C_{A_{1}S_{6}} \) on the self-assembled morphology was examined. The other system parameters were kept constant: \( A_{19} \) and \( S_{6} \) concentrations were \( C_{A_{19}} = 4.0 \% \) and \( C_{S_{6}} = 3.2 \% \), respectively and the block copolymer was \( \frac{1}{6} \), that is, \( A_{1}S_{6} \). Its concentration was varied as \( C_{A_{1}S_{6}} = 2.0 \%, 3.0 \%, 5.0 \%, 13.0 \%, 20.0 \%, 25.0 \%, \) and \( 30.0 \% \). Fig. 2 shows the final morphologies as a function of \( A_{1}S_{6} \) concentration. With increasing concentration, the system undergoes a transition from well-defined, single core, soluble core–shell assemblies (Fig. 2a and 2b) to associating morphologies with internal, multicore structures. The intermediate states correspond to the core–shell assemblies showing increasing adhesion, which translates to first chain-like assembly and, at larger adhesion, more compact packing. We note that the exact assembly morphology is subject to simulation system size, i.e. when the assemblies start aggregating and for example, the elongated chain (Fig. 2d) or the multicore particle (Fig. 2e) formed in the simulations could actually correspond to macroscopic aggregation, given a larger simulation system. Similarly, the system spanning assemblies (Fig. 2f-h) are subject to system periodicity in their morphology. Hence, in our analysis and discussing the results, we focus on changes in the internal structure and adhesion mechanisms.

The cross-sections of the single core aggregates formed at 2 % and 3 % block copolymer concentration show a well-defined core-double shell structure. The highly solvophobic components form spherical core composed of the \( A_{19} \) homopolymer and the more solvophobic block of the copolymer. The outer shell of the assembly is by the weakly solvophobic block of the copolymer and the \( S_{6} \) homopolymer. Correspondingly, in the multicore assembly, small cores of the highly solvophobic components are surrounded by the weakly solvophobic blocks and homopolymer.

Increasing the concentration from 2.0 % to 5.0 % reveals the difference in assembly process between the single core and the multicore assemblies, see Fig. 3. For both type of assemblies, first cores composed of the highly solvophobic particles formed (Fig. 3a and 3f). These evolved into core-double shell assemblies in the growth process (Fig. 3b and 3g). Coalescence of these small core-double shell aggregates lead to formation of the final core-double shell aggregates in the single core assembly (Fig. 3c-e). Coalescence of the aggregates decreases their solvent accessible surface which aids the 2.0 % concentration of block copolymer chains in the system in coating the highly solvophobic core surface. The assembly formation is guided by the low copolymer concentration – the system does not have enough copolymer chains to stabilize small aggregates. On the other hand, at 5.0 % block copolymer concentration, the copolymer concentration is high enough to stabilize the small single core-double shell aggregates. Due to the weakly hydrophobic character of the \( S_{6} \) polymer and the corresponding block of the copolymer \( A_{1}S_{6} \), the small single core-double shell aggregates gather together to form multicore aggregates (Fig. 3h-j). Consequently, it can be concluded that single core-double shell aggregates form via a combination of initial nucleation, growth, and aggregate coalescence, while the multicore aggregate structure arises from two of these sequences superposed, one corresponding to formation of the small initial aggregates and their growth and coalescence and another, slower one, to the assembly of the formed aggregates and corresponding response.

Analysis of the aggregate structures reveals that increasing the block copolymer concentration leads to the number of highly solvophobic cores increasing (see Fig. 4). Furthermore, the number of cores \( N_{c} \) versus copolymer concentration \( C_{A_{1}S_{6}} \) exhibits a differ-

![Fig. 2. Effect of increasing copolymer \( A_{1}S_{6} \) concentration on the assembly configurations. The examined systems correspond to keeping \( A_{19} \) and \( S_{6} \) concentrations constant at \( C_{A_{19}} = 4.0 \% \) and \( C_{S_{6}} = 3.2 \% \) while varying the \( A_{1}S_{6} \) block copolymer concentration in solvent. The block copolymer concentration increases from (a) to (h) with (a) 2.0 %, (b) 3.0 %, (c) 4.0 %, (d) 5.0 %, (e) 13.0 %, (f) 20.0 %, (g) 25.0 %, and (h) 30.0 %. Solvent beads are omitted for clarity. The coloring of particles follows Fig. 1.](image-url)
ent slope for the single core and multicore regions. The slope change occurring between 4.0 % and 5.0 % copolymer concentration can be taken as the indicator for the transition from single core to multicore assembly.

Multicore aggregates are clearly present in copolymer concentration higher than 4 %. The significance of the finding is that, in this type of system, to have multicore aggregation, a minimum concentration of the stabilizing interfacial polymer, here the block copolymer, is essential. We call this limit the critical multicore aggregate concentration (CMAC). This is presented in a schematic diagram in Fig. 5. In copolymer concentrations lower than CMAC, the amount of block copolymer beads S at the core surface and Ncore is the number of highly hydrophobic A beads forming the core. A cut-off distance of 0.9 is used in defining neighboring DPD beads. For determining hydrophobic core surface particles Ncore, either a W or S bead need to be within cut-off from an A bead in the analysis. Ncore is calculated over all cores in each system. A sharp increase in ρs versus CA1S6 curve, between 4 % and 5 % is detected, corresponding to the slope change in the Nc versus CA1S6 curve. Here, we observe a CMAC of around 4 % copolymer for this specific system. We emphasize that the significance of the finding is that this limit exists: the absolute number is clearly dependent on the examined system, for example, concentration of the other components, the level of solvophobicity of the polymers (chemistry of the components), chain lengths, and temperature.

3.2. Concentration ratios

Next the concentration ratios CRAA and CRAS were varied. Here, CRAA is defined as (A19 chains):(A1S6 chains) and CRAS as (A1S6 chains):(S6 chains), i.e. both by the ratio of the number counts of the respective chains. The total solid concentration was kept constant at 20.2 %. The solvent concentration in all studied systems was 79.8 % corresponding to 153,312 solvent beads in the box 40 \( R_c \times 40 \ R_c \times 40 \ R_c \) in size.

Fig. 6 shows that increasing CRAA induced a transition from multicore to single core structure (see the cross sections in Fig. 6). Increasing the number of A19 chains while decreasing the number of A1S6 chains resulted in the block copolymers no longer

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**Fig. 3.** Assembly process leading to single core (top row) and multicore assemblies (bottom row). The snapshots correspond to time evolution of the system from left to right for (a)-(e) 2 % and (f)-(j) 5 % of copolymer A1S6. The snapshots correspond to (a) 3.0 \( \times 10^3 \), (b) 3.0 \( \times 10^4 \), (c) 1.2 \( \times 10^5 \), (d) 1.8 \( \times 10^4 \), (e) 5.0 \( \times 10^3 \), (f) 3.0 \( \times 10^4 \), (g) 4.0 \( \times 10^3 \), (h) 2.5 \( \times 10^4 \), (i) 4.0 \( \times 10^3 \), and (j) 5.5 \( \times 10^3 \) simulation timesteps. The examined systems correspond to keeping A19 and S6 concentrations constant at \( C_{A19} = 4.0 \ % \) and \( C_{S6} = 3.2 \ % \).

**Fig. 4.** \( \rho_s^* \) and number of the solvophobic cores Nc versus copolymer A1S6 concentration CA1S6. The examined systems correspond to keeping A19 and S6 concentrations constant at \( C_{A19} = 4.0 \ % \) and \( C_{S6} = 3.2 \ % \).
being sufficient to form a shell around the cores. As before, to reduce interfacial surface tension between the highly solvophobic core surfaces and solvent, the cores fused. Correspondingly, the $q^*$ curve showed a decrease in adsorbed $A_{1S6}$ on the highly solvophobic cores.

Fig. 6 also shows by the adsorbed $S_6$ (SA%) versus CR $AA$ data that an increase of the number of $A_{19}$ chains (and the corresponding decrease in the number of block copolymer chains) lead to $S_6$ chain adsorption to the aggregate first increasing and then with an even larger CR $AA$, decreasing. This is because the highly hydrophobic cores first increased in size and simultaneously the $A_{1S6}$ concentration decreased as CR $AA$ increased. This led to the available contact area between the highly solvophobic cores and the $A_{1S6}$ chains increasing, which promoted adsorption of the $A_{1S6}$ chains and resulted in less steric hindrance. Consequently, $A_{1S6}$ chains can cover the highly solvophobic core better and more $S_6$ chains adsorbed on the surface. However, when CR $AA$ increased further, the $A_{1S6}$ was no longer sufficient to coat the entire core surface. This resulted in more exposed surface for the cores, which repelled some of the $S_6$ chains.

The effect of CR $AS$ = ($A_{19}$ chains):($A_{1S6}$ chains) variation in the range 0.5–6 is presented in Fig. 7 a-e. A decrease of CR $AS$ clearly pushes the assembly toward single core aggregate formation. However, a complete transition from the multicore assembly does not occur in the examined...
Fig. 7. Effect of varying the concentration ratio $\text{CR}_{42} = (A_1 S_6 \text{ chains})/(S_6 \text{ chains})$. The system studied contains $A_1$ in concentration 4.0 % and $A_1 S_6$ and $S_6$ in varying concentration ratio $\text{CR}_{42}$ in solvent. The snapshots correspond to $\text{CR}_{42}$ (a) 0.5, (b) 1.0, (c) 3.5, (d) 4.5 and (e) 6.0. (f) $\rho^*$ and core number count $N_c$ curves versus $\text{CR}_{42}$. Total solid concentration is kept constant at 20.2 %. Solvent and $S_6$ beads are omitted for clarity. The coloring of particles follows Fig. 1. Snapshots showing more details and the cross-section cuts of the aggregates are presented in the Supporting Information, Figures S2 and S3, respectively.

Fig. 8. Final snapshots corresponding to a polymer system with $A_1$ (4.0 %), $A_1 S_6$ (13.0 %) and $S_m$ (3.2 %), with varying $S_m$ chain length $m$ in solvent. The snapshots correspond to a) $m = 6$, b) $m = 18$, c) $m = 30$, and d) $m = 42$. In e), $\rho^*$, SA and $N_c$ curves versus $m$ are plotted. Total solid concentration is kept constant at 20.2 %. Solvent beads are omitted for clarity. The coloring of particles follows Fig. 1. The cross-section visualizations of the aggregates are presented in the Supporting Material Figure S4.
range. However, an even smaller CRAS can be expected to lead to single core formation, see discussion in Section 3.1. Furthermore, increasing CRAS leads to an increase in the number of highly solvophobic cores in the examined system (Fig. 7f). The considerations presented before concerning aggregate fusion until block copolymer stabilization is sufficient to stabilize the assemblies are valid here as well.

Notably, \( \rho^\ast \) passes through a maximum with increasing CRAS. The adsorbed \( S_6 \) chains act as a binder for small aggregates and pack with the \( S_6 \) blocks of the copolymer such that the copolymer block elongation decreases. This leads to less elastic deformation penalty in the conformations. An increasing copolymer concentration corresponds to the concentration of \( S_6 \) decreasing in an effective coating of the solvophobic cores. This indicates that the copolymer and \( S_6 \) can compensate each other in the coating formation.

### 3.3. Chain length variation of the weakly solvophobic homopolymer

The effect of the chain length on the overall aggregation of the homopolymer chains \( S_m \) is essential as this polymer species facilitates the agglomeration of the multicore assemblies. We varied \( m \) between 5 and 42 DPD beads while keeping the total solids concentration constant. Fig. 8 shows that increasing \( m \) decreased the concentration of \( S_m \) in solvent as the longer \( S_m \) chains were mainly adsorbed to the aggregate. Fig. 8f presents a quantification of this by the adsorbed \( S_m \) percentage (SAA%) versus \( m \). The data shows an increasing trend for the adsorption with increasing chain length, with the longer chain lengths leading to almost total adsorption of the \( S_m \). Increasing the chain length lead additionally to a proportionally higher connectivity between the beads. This restricted the motions of the beads and promoted adsorption. On the other hand, increasing \( m \) decreased the chain solubility since polymer solubility decreases with an increasing degree of polymerization. Consequently, the chains preferred to diffuse inside the aggregate or to adsorb to the aggregates. This reduced their contact with solvent.

Increasing \( m \) did not change the multicore aggregate structure. To quantify this, \( \rho^\ast \) and \( N \) curves versus \( m \) are presented in Fig. 8e. The data shows no significant changes within the examined \( m \) range.

### 4. Conclusions

Recently, multicore or multicore–multicompartment assemblies have been produced successfully by various approaches such as self-assembly of triblock copolymers [28,57–60], amphiphilic alternating copolymers [26], linear ABCBA penta-block copolymers [61], and via triblock copolymer non-linear architectures such as star-shaped, miktoarm, and dendritic [27,62,63]. Despite all these studies demonstrating multicore and multicompartment assembly morphologies have been established remain relatively complex. Additionally, multicore assembly and control of the multicompartment assemblies remain open topics at the microscopic level.

Here, we presented a simple three component linear polymer system that self-assemblies to multicore assemblies with two co-existing characteristic structural assembly length scales. In particular, the system corresponds to a cost-efficient and simple block-copolymer framework containing a strongly solvophobic homopolymer, a weakly solvophobic species and an amphiphilic block copolymer in a solvent medium. We found that the examined model system self-assembles into two main self-assembly structures: 1) single core and 2) multi core assemblies. The main findings center around the systematic design and tuning of the assembly characteristics and emergence of the multiple length scales allowed by the system parameters. Specifically, we mapped on the selected model system the dependency of the assembly structure and the single core to multi core assembly transition on the copolymer concentration, component concentration ratios, and chain length of the weakly solvophobic homopolymer acting as binder in the multicore assembly.

At low block copolymer concentrations, single core assemblies formed while an increase in the block copolymer led to the assembly transitioning to multicore. The findings indicate that a minimum concentration of the block copolymer is essential to have multicore aggregates. We postulate that this leads to an effective critical multicore aggregate concentration (CMAC) for the examined system and its analogues. The results suggest that at copolymer concentrations lower than CMAC, the polymer system has less block copolymer chains than required for complete coating of the surface of the solvophobic cores. Thus, reducing the interfacial surface tension by the amphiphilic block copolymer remains incomplete. A further reduction in the overall aggregation free energy can be achieved by the highly solvophobic cores merging to form larger cores that have correspondingly a smaller total surface area to coat by the amphiphilic copolymers. Hence, CMAC corresponds to the concentration at which the surface tension reduction by the copolymer chains counters the free energy gain of the cores merging, leading to stabilization of the small cores. Given sufficient corona attraction (in this work, the weak solvophobicity of the \( S \) polymer component), the small aggregates may form multicore assemblies. It is worth noting that a highly solvophilic corona would lead to small, soluble core–shell particles, instead of the multicore assembly.

In line, the simulations also showed that a transition from multicore to single core structures can be achieved by increasing the number of highly solvophobic homopolymer chains while decreasing the number of copolymer chains such that the total solids concentration remained constant. Varying the number ratio of the block copolymer chains and the weakly solvophobic homopolymer chains again resulted in the system transitioning from multicore assembly to single core assembly at low block copolymer to weakly solvophobic homopolymer ratio. Both transitions can be understood in terms of the change resulting in an insufficient amount of block copolymers to form a shell around the cores.

A different mechanism of assembly change was observed when varying the weakly solvophobic homopolymer chain length. Increasing the length of the weakly solvophobic homopolymer led to decrease of its concentration in solvent as the longer chains are mainly adsorbed onto the aggregate shell. This is a direct consequence of the decrease in solubility by the increase of length. Additionally, as adsorption of more and longer chains onto the corona increase both the corona size and the extension of the corona polymers to the solvent phase, the corona becomes potentially more adhesive, promoting multicore assembly in comparison to core–shell particle formation. In total, the results lead to conclusion that an interplay between the interfacial surface tension driving for hydrophobic core growth, the availability of enough copolymer chains to stabilize the formed solvophobic cores, and a sufficient adhesion stickiness (here, the weak hydrophobicity) of the stabilizing corona are responsible for multicore aggregate formation and the stability of the assembly. We mapped the dependency of these for several system variables in a simple, generalizable three component polymer system.

Notably, multicore aggregates have significant advantages in comparison to regular core–shell micelles: the cores provide microenvironments differing from their surroundings, and for stimuli-responsive polymer system, parameters such as pH, salt concentration, temperature, electromagnetic field, light,
ultrasound, and enzymes, can be used for tuning [32–34,36,37,64,65]. This is interesting for high-precision solubilization and control of release, e.g. in sequential drug delivery type applications where the cores are loaded with multiple drug types released stepwise [66,67]. The multicore, confined microenvironment capsules can protect the carried species, for example, drugs or reagents. For drugs, this means enhanced prevention of enzymatic degradation, improved biodistribution, and decrease of drug uptake in unwanted tissues [66,67]. For catalysis and reactions platforms, a corresponding enhancement of reaction and product control is obtained [33,34].

The presented findings agree with previously reported findings on alkyl-ethoxylate and pluronics block copolymer systems dependency on amphiphilic component concentrations in particular assembly and assembly morphologies [68–71]. Systematic assembly studies besides the alkyl-ethoxylate and pluronics model systems remain rare but findings include e.g. amphiphile concentration based controlled melting of poly(butyl acrylate-b-acrylic acid) micelles [72] and directing assembly structure of sodium poly(isoprene-b-methacrylate) micelles [73]. At general level, amphiphiles and their concentration are well-known to control assembly morphologies in polymeric systems, for recent reviews see e.g. Refs. [74,75]. However, the responses have been demonstrated for individual polymer mixtures. Here, we mapped the dependency of system parameters for an easily generalizable polymer system and identify specific requirement of amphiphilic component for the dual length scale, multicore assembly. The significance of the current computational work is that the revealed trends and observed transitions can aid in designing polymer systems for controlled multicore assembly.

CRediT authorship contribution statement

Sousa Javan Nikkhah: Methodology, Investigation, Conceptualization, Visualization, Writing – original draft, Writing – review & editing.

Maria Sammalkorpi: Supervision, Conceptualization, Resources, Writing – review & editing, Funding acquisition, Project administration.

Data availability

Data associated with the manuscript is available at https://doi.org/10.23729/8dc295cd-4915-4536-acbc-d0603d54bfb4.

Declaration of Competing Interest

The authors declare the following financial interests/personal relationships which may be considered as potential competing interests: [Maria Sammalkorpi reports financial support was provided by Kemira Oyj. Sousa Javan Nikkhah reports financial support was provided by Kemira Oyj].

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Appendix A. Supplementary material

Supplementary data to this article can be found online at https://doi.org/10.1016/j.jcis.2022.12.119.

References


